

Device-independent quantification of Einstein-Podolsky-Rosen steerability

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Workshop on Quantum Nonlocality, Causal Structures,
and Device independent Quantum Information

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National Cheng Kung University, Taiwan

collaborators:

Costantino Budroni, Yeong-Cherng Liang and Yueh-Nan Chen

Device-independent quantification of Einstein-Podolsky-Rosen steerability

Outline

Steering and local hidden state model

Hierarchy relation between steering, entanglement, and Bell nonlocality

Motivation

Characterizing quantum correlations and the moment matrix

The moment matrix of single party state

Device-independent quantification of steerability

Summary and outlook

Steering and local hidden state model

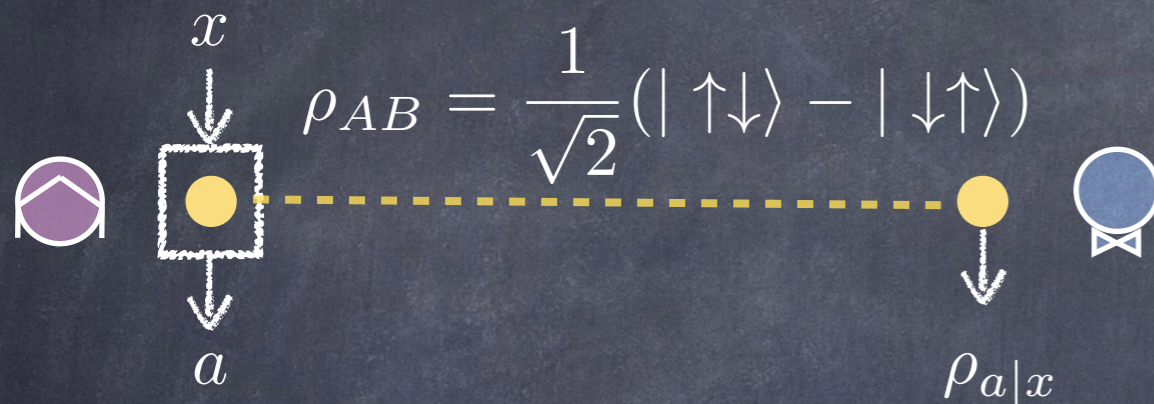
A simple demonstration of steering

$$\rho_{AB} = \frac{1}{\sqrt{2}}(|\uparrow\downarrow\rangle - |\downarrow\uparrow\rangle)$$



Steering and local hidden state model

A simple demonstration of steering

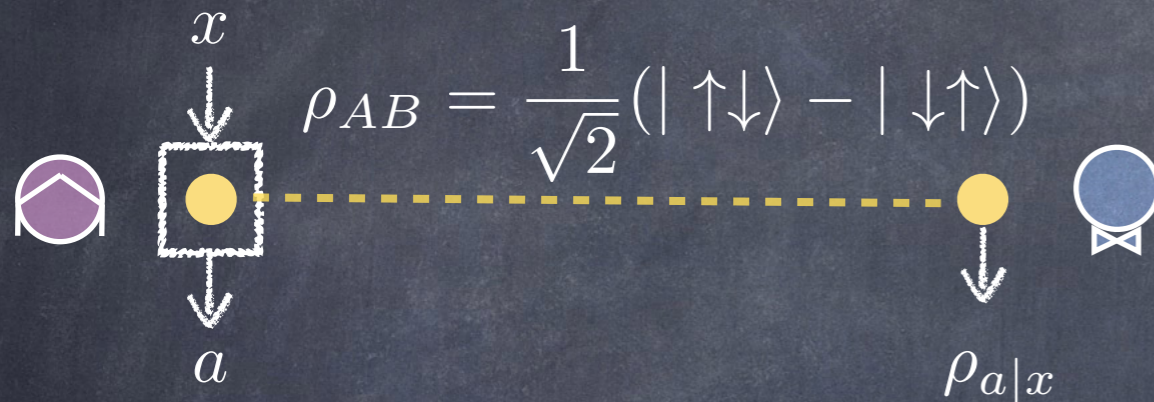


$$\rho_{a|x} = \text{tr}_A [M_{a|x} \otimes \mathbb{I} \rho_{AB}]$$

(subnormalized state)

Steering and local hidden state model

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$\{|0\rangle, |1\rangle\}$ eigenstates of σ_z

$\{|+\rangle, |-\rangle\}$ eigenstates of σ_x

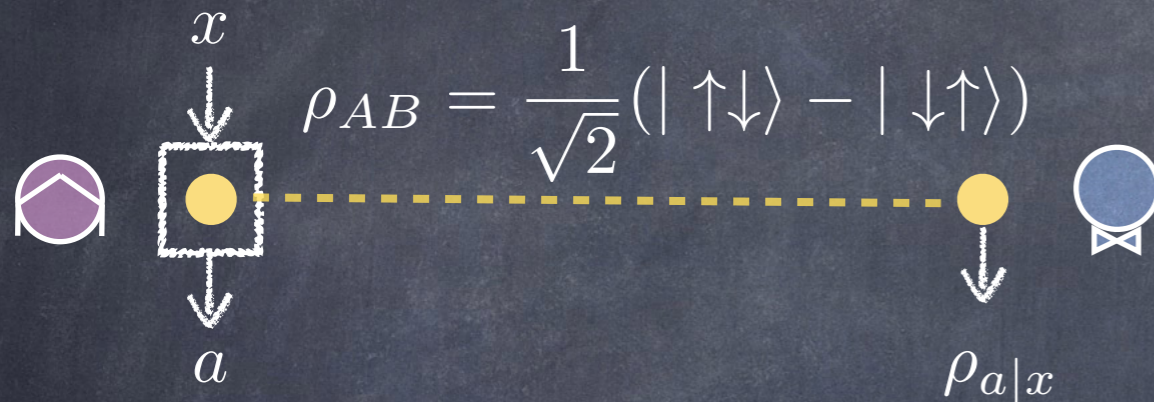
Alice's measurement	$\hat{\rho}_{a x}$
σ_z	$\{ 0\rangle, 1\rangle\}$
σ_x	$\{ +\rangle, -\rangle\}$



“steering”
 — by Schrödinger

Steering and local hidden state model

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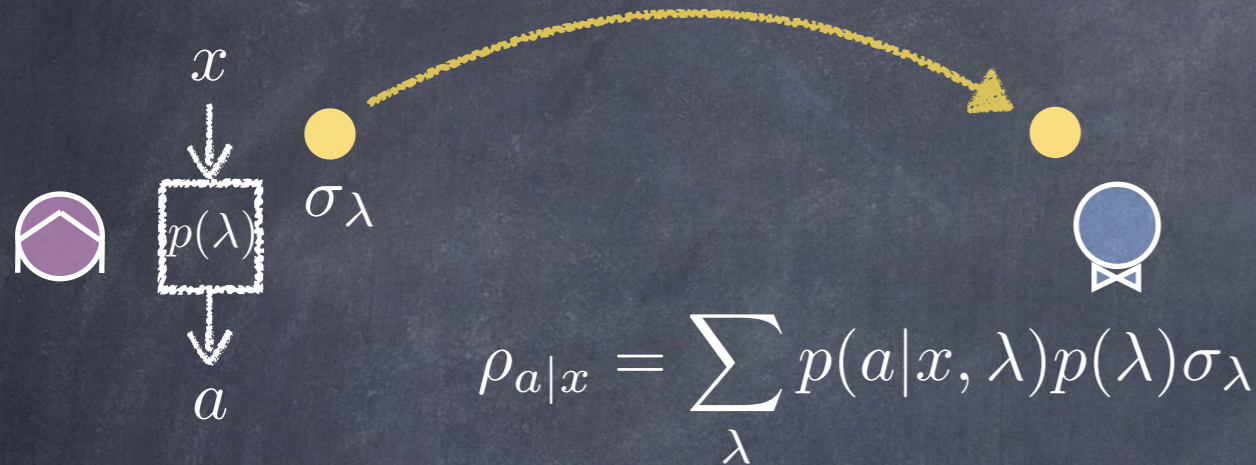


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How can Bob check if Alice steers his state?

Steering and local hidden state model

A simple demonstration of steering



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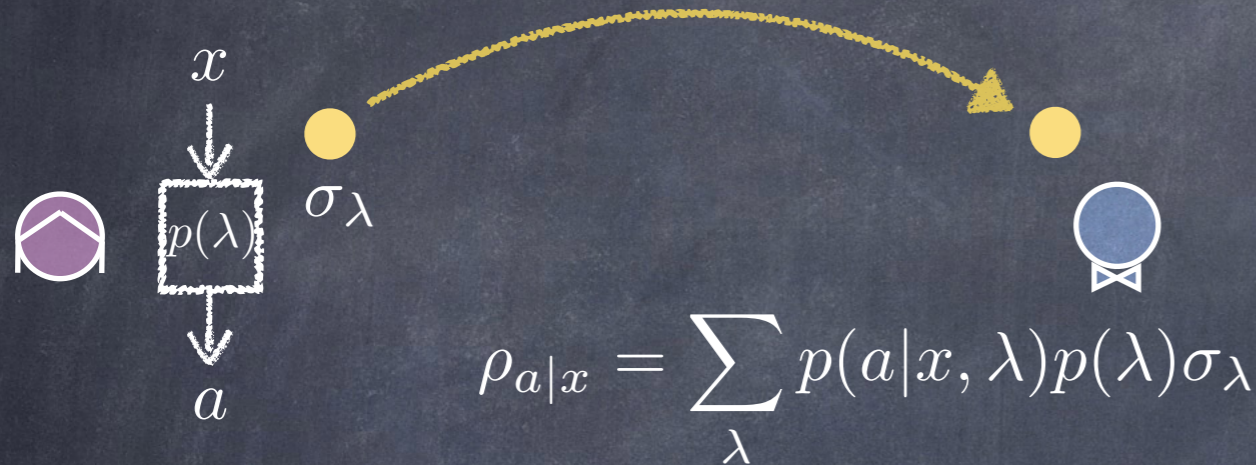
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How can Bob check if Alice steers his state?

$\forall a, x, \exists \{\sigma_{\lambda}\}, \text{ s.t. } \rho_{a|x} = \sum_{\lambda} p(a|x, \lambda)p(\lambda)\sigma_{\lambda}$ local hidden state model

Steering and local hidden state model

A simple demonstration of steering



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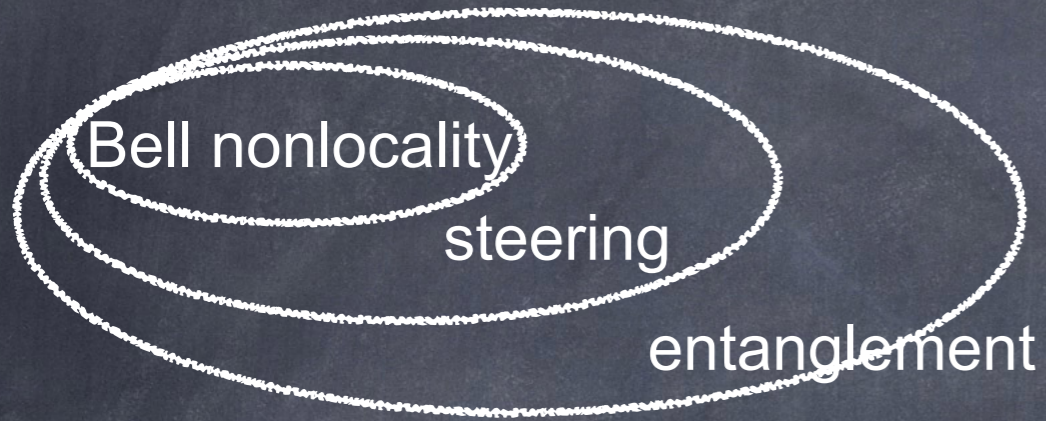
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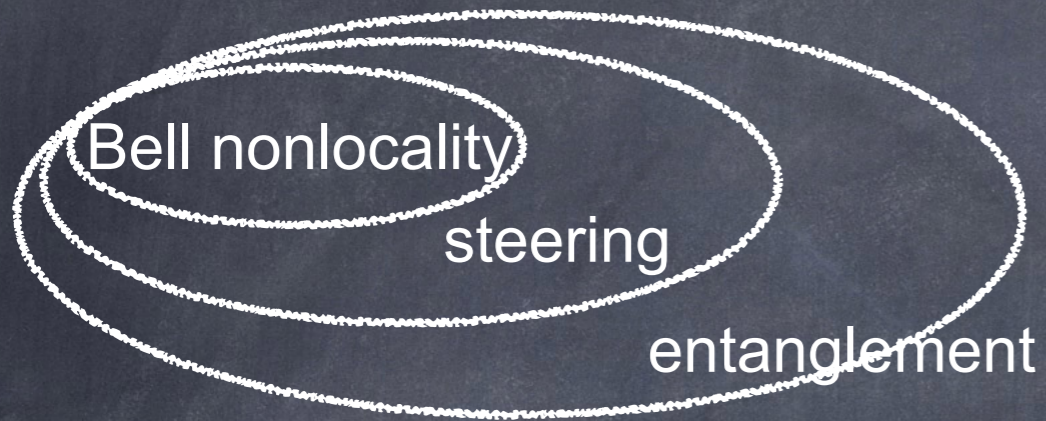
↔ non-steerability from Alice to Bob

Hierarchy relation between steering, entanglement, and Bell nonlocality



-H. M. Wiseman, S. J. Jones, and A. C. Doherty
Phys. Rev. Lett. **98**, 140402 (2007).

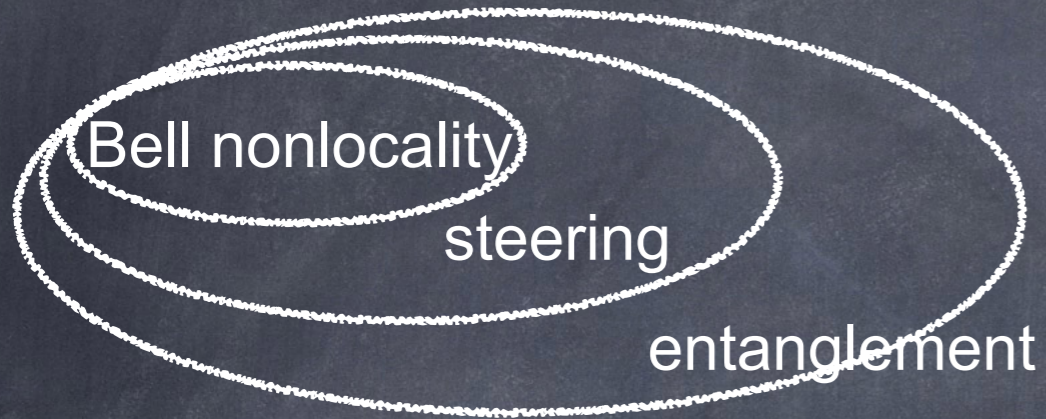
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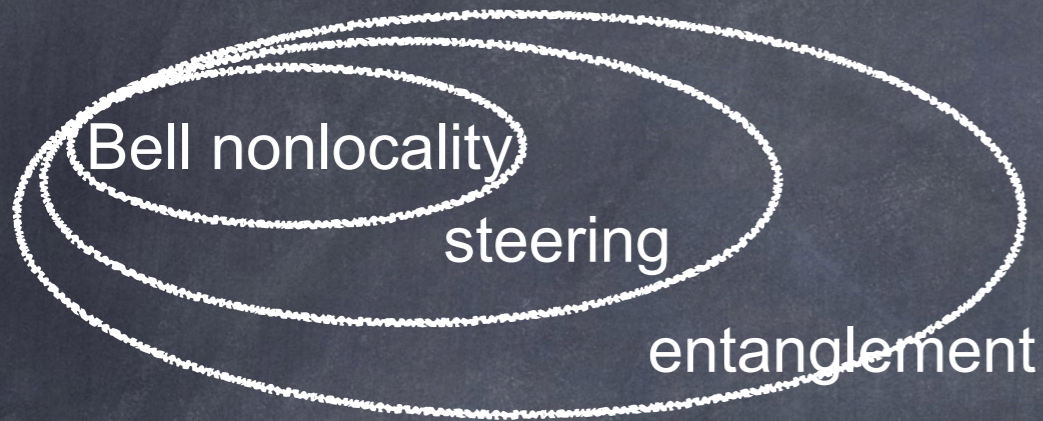


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Violation of a steering inequality certifies entanglement (one-sided device-independence).

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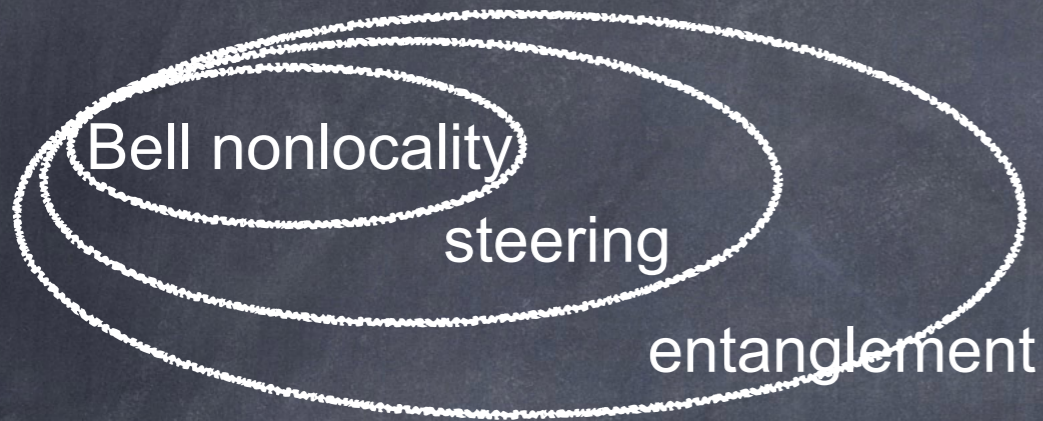
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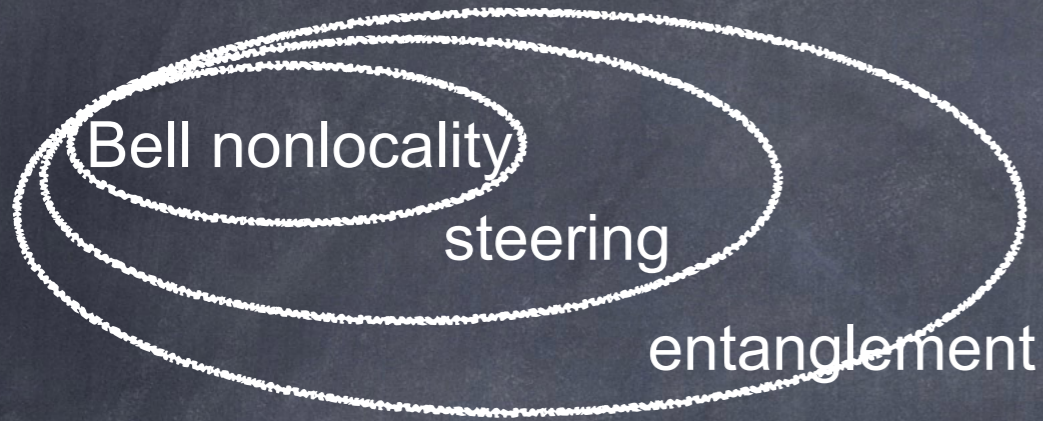
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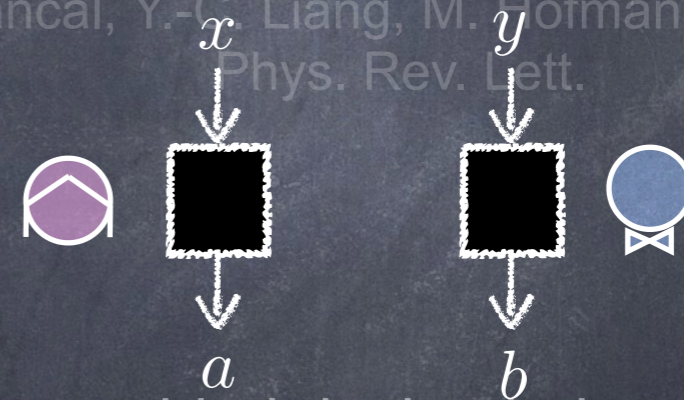
Violation of a Bell inequality certifies entanglement (full device-independence)

T. Moroder
 violation

$$\min \mathcal{N}(\rho_{AB})$$

such that $\sum_{abxy} I_{abxy} P(a, b|x, y) = v$

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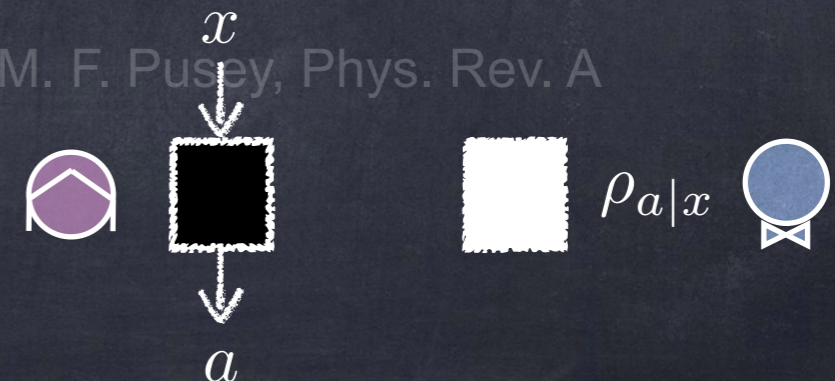
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$$\min \mathcal{N}(\rho_{AB})$$

such that $\sum_{ax} \text{Tr}(F_{a|x} \rho_{a|x}) = u$

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Motivation

lower bound on the degree of steerability for given Bell inequality violation

$$\min_{\rho_{AB}} \mathcal{N}(\rho_{AB})$$

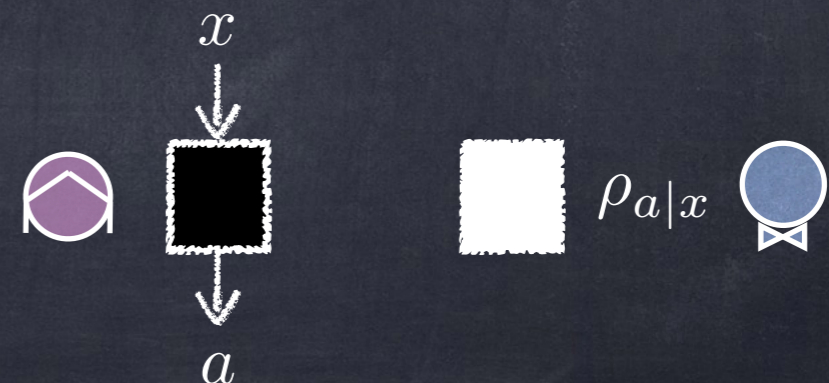
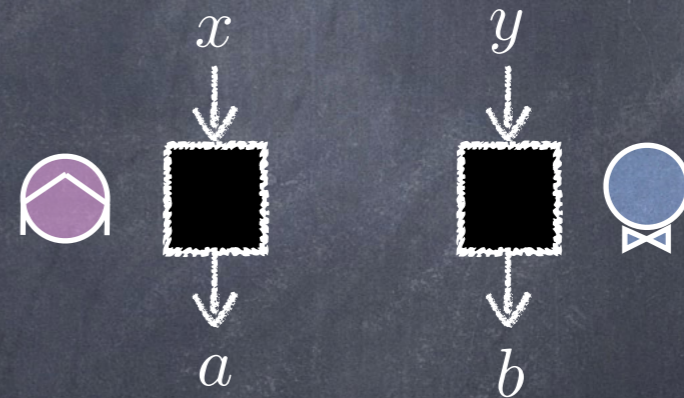
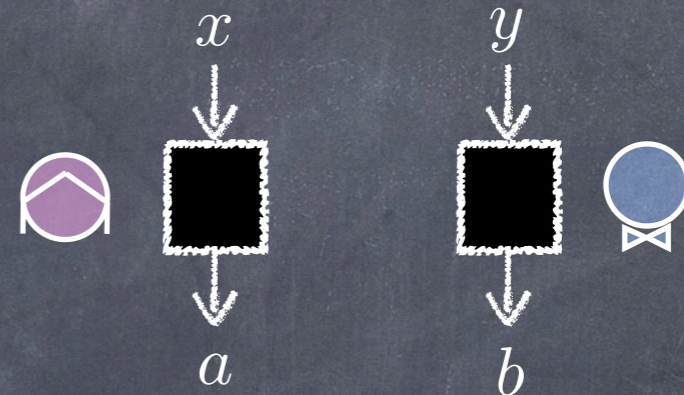
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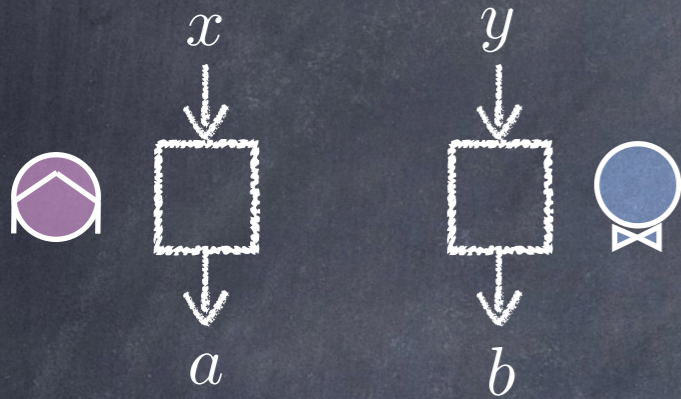
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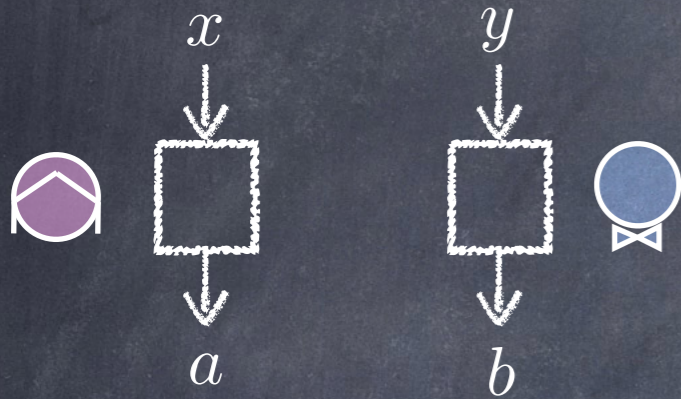
Characterizing quantum correlations and the moment matrix

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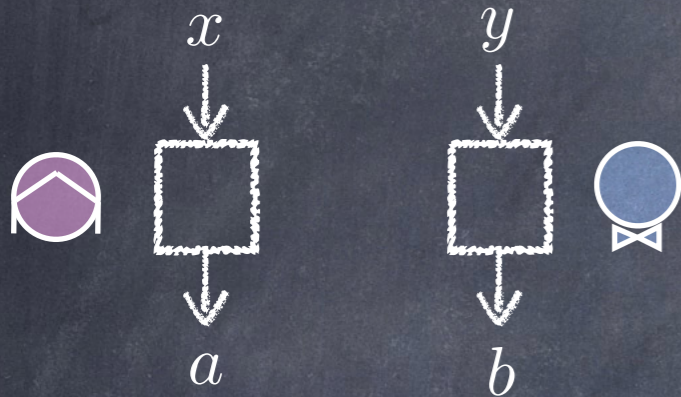
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$$\{P(a, b|x, y)\} \in Q$$

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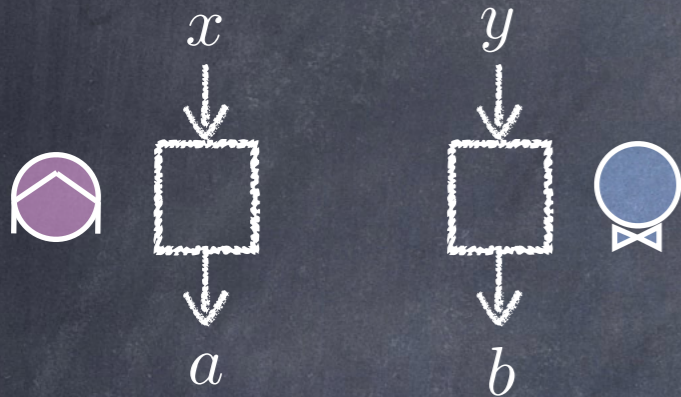
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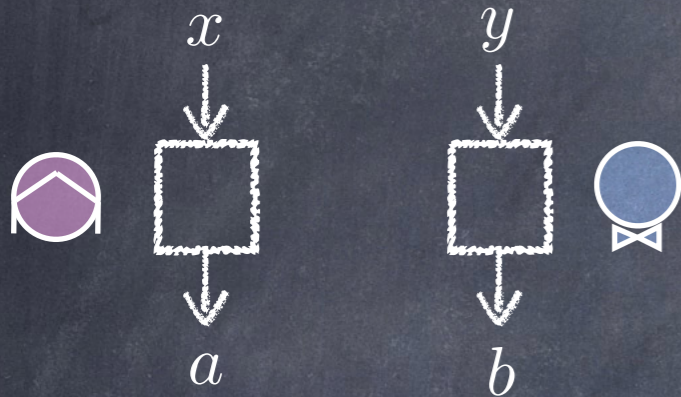
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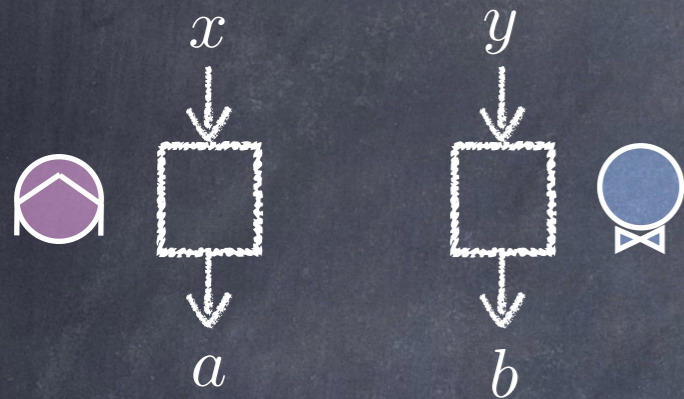
$$\begin{aligned} \mathcal{S}^{(1)} &= \{E_{a|x}\} \cup \{E_{b|y}\} \\ &= \{S_1, \dots, S_n\} \end{aligned}$$

$$\Gamma = \begin{pmatrix} \dots & \dots & 0 \\ \dots & \dots & \dots \\ \dots & \dots & \dots \end{pmatrix} \rightarrow \text{Tr}(E_{a|x} \otimes E_{b|y} \rho_{AB}) = P(a, b|x, y)$$

unknown complex number

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$$\Gamma^{(1)} \geq 0 \iff \{P(a, b|x, y)\} \in Q^{(1)}$$

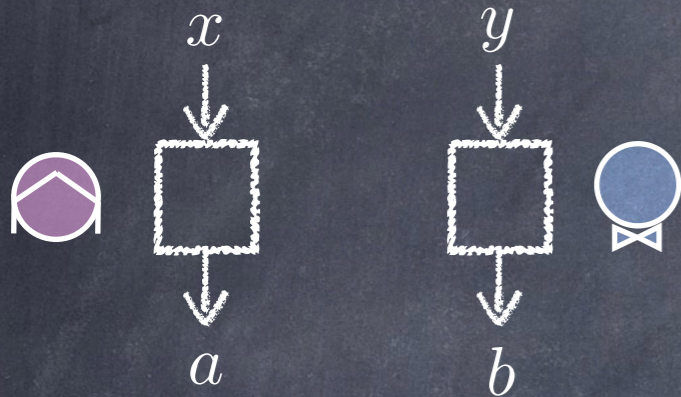
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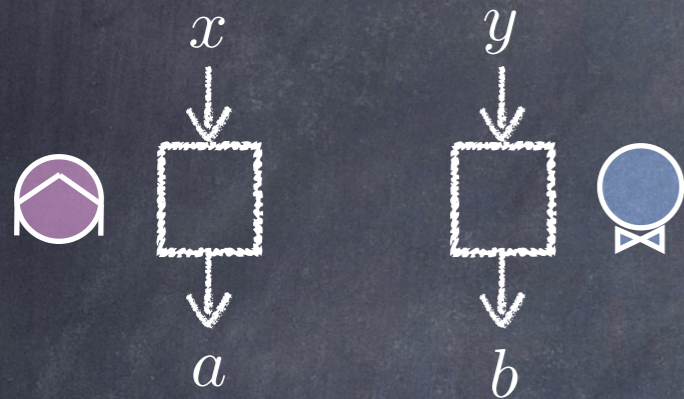
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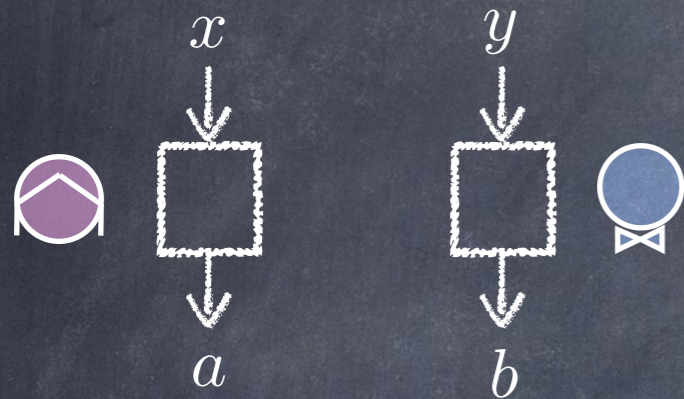
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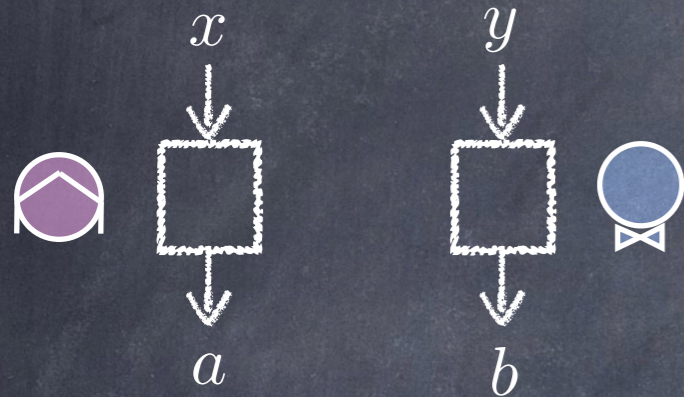
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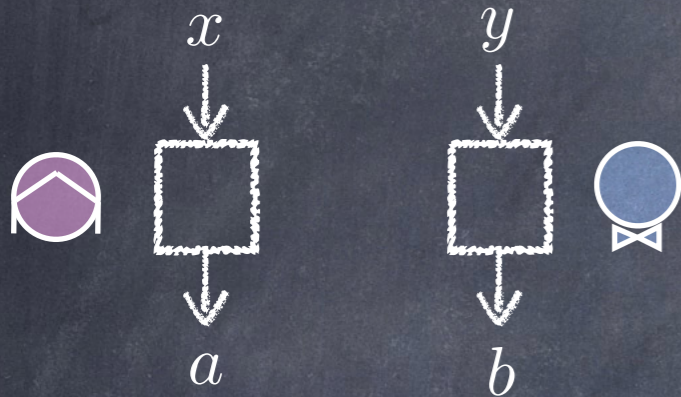
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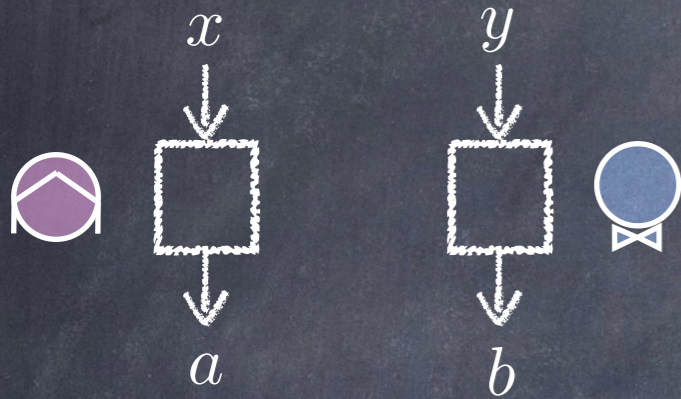
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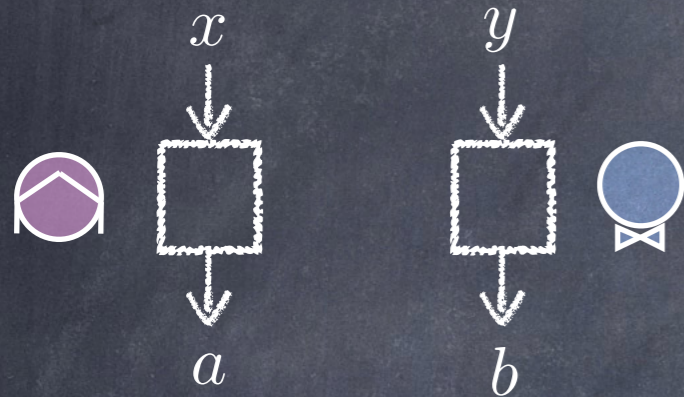
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Steering and I

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Summary and outlook

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$$\Gamma[\rho_{AB}] = \Lambda[\rho_{AB}] = \sum_{ij} |j\rangle\langle i| \text{Tr}[S_i^\dagger S_j \rho_{AB}] \quad \text{a global CP map}$$

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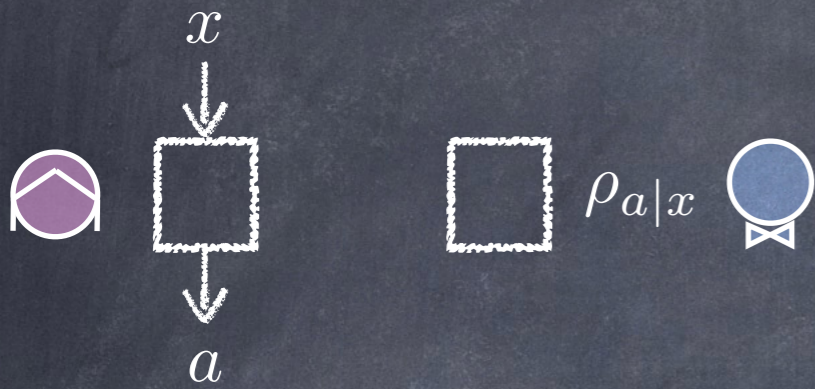
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The moment matrix of assemblage



consider a local map on Bob's state

$$\chi[\rho_B] = \sum_{ij} \text{Tr}[B_j^\dagger B_i \rho_B]$$

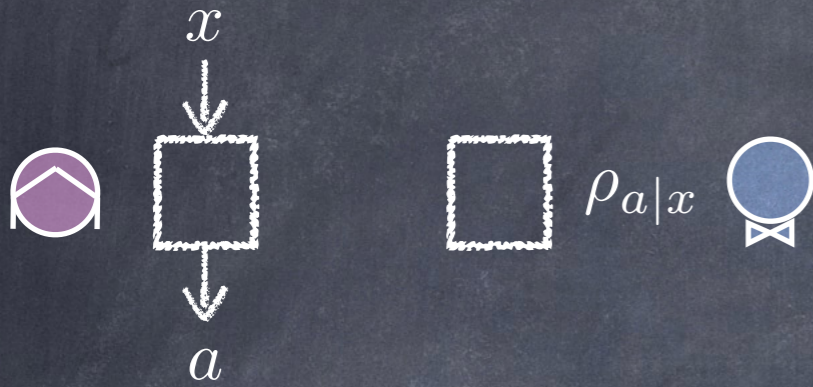
The moment matrix of assemblage



consider a local map on Bob's state

$$\chi[\hat{\rho}_{a|x}] = \sum_{ij} \text{Tr}[B_j^\dagger B_i \hat{\rho}_{a|x}]$$

The moment matrix of assemblage



consider a local map on Bob's state

$$\chi[\hat{\rho}_{a|x}] = \sum_{ij} \text{Tr}[B_j^\dagger B_i \hat{\rho}_{a|x}]$$

define the "moment matrix" of Bob's assemblage:

$$\chi[\rho_{a|x}] = p(a|x) \sum_{ij} \text{Tr}[B_j^\dagger B_i \hat{\rho}_{a|x}]$$

The moment matrix of assemblage



consider a local map on Bob's state

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define the "moment matrix" of Bob's assemblage:

$$\chi[\rho_{a|x}] = p(a|x) \sum_{ij} \text{Tr}[B_j^\dagger B_i \hat{\rho}_{a|x}]$$

ex. two settings y, y' , three outcomes for each setting $b \in \{0, 1, 2\}$ (first level)

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The moment matrix of assemblage



consider a local map on Bob's state

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keep going to higher level...

The moment matrix of assemblage



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keep going to higher level...

convergence:



Steering and I
Hierarchy relation between steering, entanglement, and Bell nonlocality
Motivation
Characterizing quantum correlations and the moment matrix

The moment matrix of single party state
Device-independent quantification of steerability
Summary and outlook

The moment matrix of assemblage

Testing Tsirelson's bounds

The moment matrix of assemblage

Testing Tsirelson's bounds

$$\begin{aligned} & \max I \cdot P \\ \text{subject to } & \chi[\rho_{a|x}] \geq 0 && \forall a, x \\ & \sum_a \chi[\rho_{a|x}] = \sum_a \chi[\rho_{a|x'}] && \forall x \neq x' \end{aligned}$$

$$I \cdot P = \sum_{a,b,x,y} I_{a,b,x,y} P(a, b|x, y)$$

The moment matrix of assemblage

Testing Tsirelson's bounds

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$$I \cdot P = \sum_{a,b,x,y} I_{a,b,x,y} P(a, b|x, y)$$

	CHSH Ineq.	I_{3322}	I_{2233}
$l = 1$	2.8284	0.3621	0.3078
$l = 2$		0.2550	0.3050
$l = 3$		0.2512	0.3050
$l = 4$		0.2509	

	Tsirelson's bound
CHSH Ineq.	$2\sqrt{2} \approx 2.8284$
I_{3322}	≈ 0.25088
I_{2233}	$(\sqrt{11/3} - 1)/3 \approx 0.3050$

The upper bound of a given Bell inequality converges (?) to Tsirelson's bound when increasing the level of hierarchy l .

Device-independent quantification of steerability

a measure of steering - steering robustness (SR) of assemblage $\{\rho_{a|x}\}_{a,x}$

$$\begin{aligned} & \min t \geq 0 \\ & \text{subject to } \left\{ \frac{\rho_{a|x} + t \tau_{a|x}}{1+t} \right\}_{a,x} \text{ unsteerable} \\ & \quad \quad \quad \{\tau_{a|x}\}_{a,x} \text{ any assemblage} \end{aligned}$$

-Marco Piani and John Watrous
Phys. Rev. Lett. **114**, 060404 (2015).

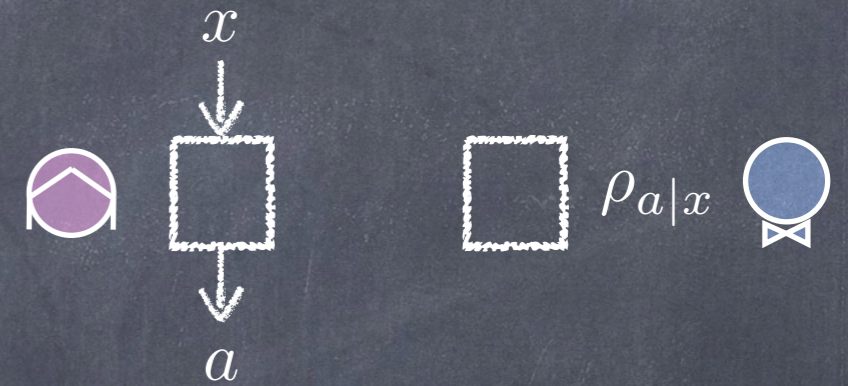
Device-independent quantification of steerability

$$\text{SR} = \min \text{tr} \sum_{\lambda} \sigma_{\lambda} - 1$$

subject to

$$\sum_{\lambda} p(a|x, \lambda) \sigma_{\lambda} - \rho_{a|x} \geq 0 \quad \forall a, x$$

$$\sigma_{\lambda} \geq 0 \quad \forall \lambda$$



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$$\sigma_{\lambda} \geq 0 \quad \forall \lambda$$

$$\min \sum_{\lambda} \chi[\sigma_{\lambda}]_{\text{tr}} - 1$$

$$\text{subject to } \sum_{\lambda} p(a|x, \lambda) \chi[\sigma_{\lambda}] - \chi[\rho_{a|x}] \geq 0 \quad \forall a, x$$

$$\chi[\sigma_{\lambda}] \geq 0 \quad \forall \lambda$$

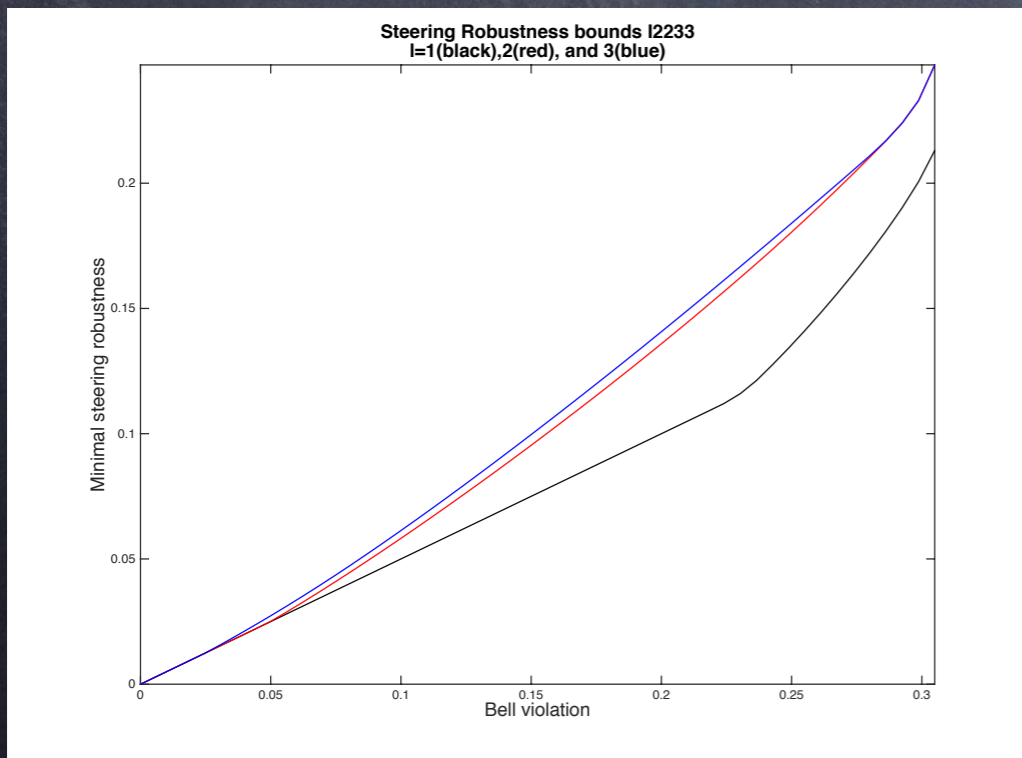
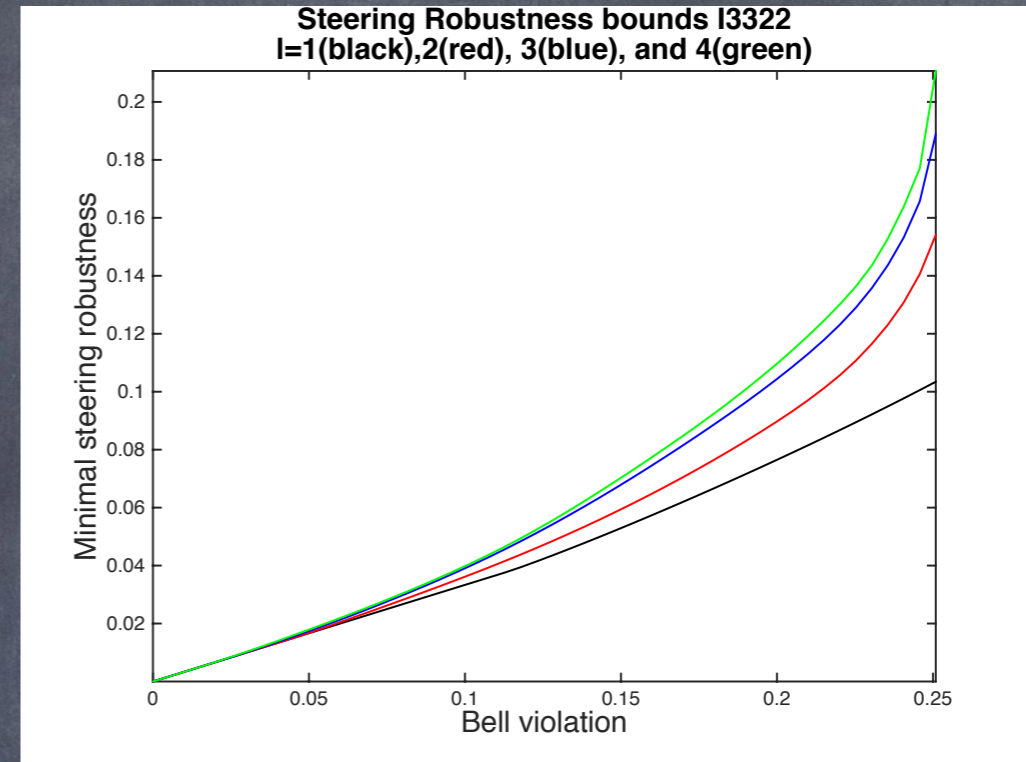
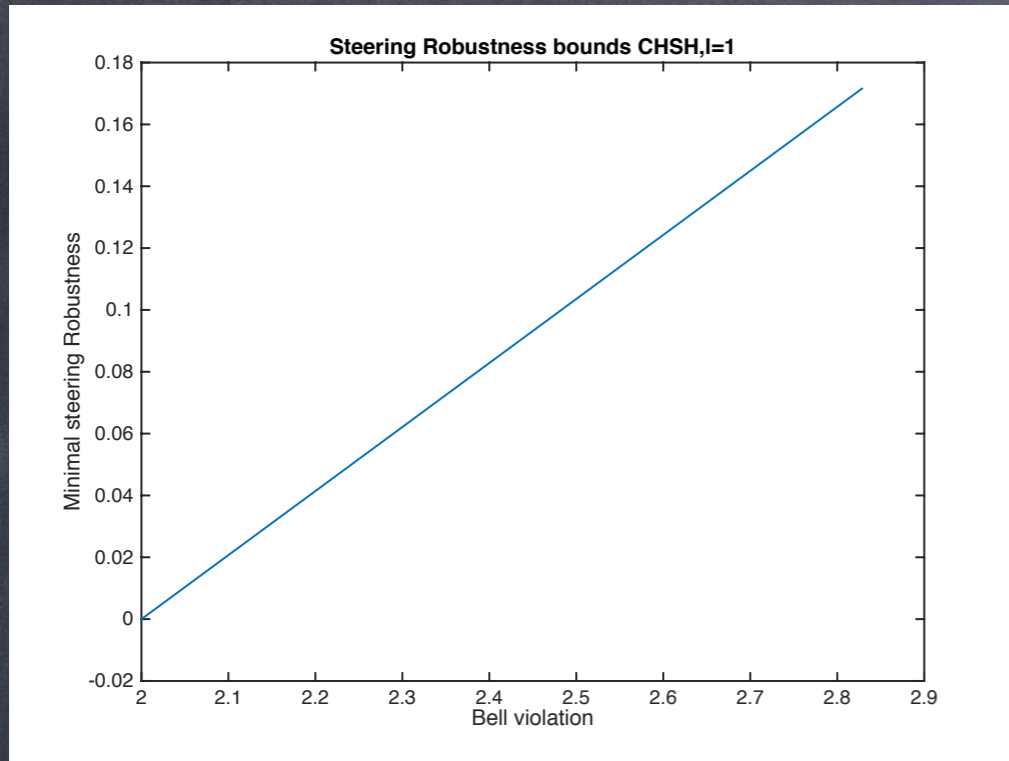
$$\chi[\rho_{a|x}] \geq 0 \quad \forall a, x$$

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$$\sum_a \chi[\rho_{a|x}]_{\text{tr}} = 1 \quad \forall a, x$$

$$I \cdot P = v,$$

Device-independent quantification of steerability



Summary and Outlook

The moment matrix of assemblage

Device-independent quantification of steerability

The gap between quantum set and our approach

Device-independent quantification of measurement incompatibility

$$\text{IR}(M_{a|x}) \geq \text{SR}(\sigma_{a|x})$$

Possibility of self-testing

Thank you for your attention!